

3.3V power supply, up to 256 nodes, 12Mbps half-duplex, RS485/RS422 transceiver

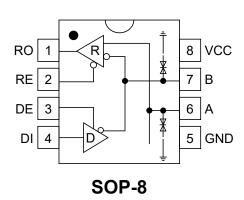
### 1.Description

The ADM3485E is a 3.3V powered, half-duplex, low-power RS-485 transceiver that fully meets the requirements of the TIA/EIA-485 standard. The ADM3485E includes a driver and a receiver, both of which can be independently enabled and disabled. When both are disabled, both the driver and the receiver output a high impedance state. The ADM3485E has a 1/8 load that allows 256 ADM3485E transceivers to be connected to the same communication bus. Error-free data transfer of up to 12Mbps is possible. The ADM3485E operates from a voltage range of 3.0 to 3.6V and features fail-safe, over temperature protection, current limit protection, over-voltage protection, and other functions.

#### 2.Features

- 3.3V power supply, half-duplex
- 1/8 unit load allows up to 256 devices on the bus
- Driver output short-circuit protection function
- Over temperature protection function
- Low power shutdown function
- Receiver open circuit protection function
- Strong anti-noise ability
- Integrated transient voltage resistance function
- Transmission rate up to 12Mbps in an electrical noise environment:

## 3. Pinning information





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### 4.Limiting Values

Parameter	Symbol	Value	Units
Supply voltage	V <sub>cc</sub>	7	V
Voltage of control port	/RE, DE, DI	-0.3 to 7	V
Bus side input voltage	A, B	-7 to 13	V
Receiver output voltage	RO	-0.3 to 7	V
Operating temperature range		-40 to 85	°C
Storage temperature range		-60 to 150	°C
Welding temperature		300	°C
Continuous power dissipation	SOP-8	400	mW

The maximum limit parameter value means that exceeding these values may cause irreversible damage to the device. Under these conditions, it is not conducive to the normal operation of the device. Continuous operation of the device under the maximum allowable rating may affect the reliability of the device. The reference point of all voltages is ground.



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### **5.Pin Functions**

Pin number	Pin name	Pin function
4	DO	Receiver output When /RE is low level: if A-B ≥ 200mV, RO=high;
1	RO	if A-B ≤ -200mV, RO=low
		Receiver output enable control
		When /RE is low level, receiver output is enabled, and RO output is available.
0	/DE	When /RE is high level, receiver output is disabled, and RO is in high
2	/RE	impedance state.
		When /RE is high level and DE is low level, the device enters low power
		consumption mode.
		Driver output enable control
		When DE is high level, driver output is available; when DE is low level, the
3	DE	output is in high impedance state.
		When /RE is high level and DE is low level, the device enters low power
		consumption mode.
		Driver input
		When DE is high level, the DI low level forces the non-inverting driver
4	DI	output A low and inverting driver output B high;
		The DI high level forces the non-inverting driver output A high and
		inverting driver output B low.
5	GND	Ground
6	А	Non-inverting receiver input and non-inverting driver output
7	В	Inverting receiver input and inverting driver output
8	VCC	Power supply





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### **6.Driver Electrical Characteristics**

 $(V_{CC}=5V \pm 5\%, T_A=T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.})$  (Notes 1, 2)

Parameter	Symbol	Conditions	Min	Тур	Max	Units
Differential output voltage (no load)	V <sub>OD1</sub>			3.3		V
Differential output voltage	$V_{OD2}$	Figure 2, $R_L$ =54 $\Omega$	1.2		V <sub>CC</sub>	V
Differential output voltage	V OD2	Figure 2, R <sub>L</sub> =100Ω	2		V <sub>CC</sub>	V
Change in magnitude of differential output voltage (NOTE1)	$\Delta V_{\sf OD}$	Figure 2, $R_L$ =54 $\Omega$			0.2	V
Common mode output voltage	V <sub>oc</sub>	Figure 2, R <sub>L</sub> =54Ω			3	V
Change in magnitude of common mode output voltage (NOTE1)	$\Delta V_{OC}$	Figure 2, R <sub>L</sub> =54Ω			0.2	V
Input high voltage	V <sub>IH</sub>	DE, DI, /RE	2			V
Input low voltage	V <sub>IL</sub>	DE, DI, /RE			0.8	V
Logic input current	I <sub>IN1</sub>	DE, DI, /RE	-2		2	μA
Output short-circuit current,short-circuit to high	I <sub>OSD1</sub>	Short-circuit to 0V~12V			250	mA
Output short-circuit current,short-circuit to low	I <sub>OSD2</sub>	Short-circuit to -7V~0V	-250			mA
Themmal shutdown threshold				140		°C
Themmal shutdown hysteresis				20		°C

(unless otherwise stated  $V_{CC}$ =3.3V±10%, Temp= $T_{MIN}$ ~ $T_{MAX}$ , typical value is  $V_{CC}$ =+3.3V,  $T_{emp}$ =25°C)

NOTE1:  $\Delta V_{\text{OD}}$  and  $\Delta V_{\text{OC}}$  are the changes in  $V_{\text{OD}}$  and  $V_{\text{OC}}$  amplitude caused by a change of DI state of the input signal.



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### 7. Receiver Electrical Characteristics

Parameter	Symbol	Conditions	Min	Тур	Max	Units
Input current (A, B)		DE=0V, V <sub>CC</sub> =0 or 3.3V, V <sub>IN</sub> =12V			125	μA
input current (A, B)	I <sub>IN2</sub>	DE=0V, V <sub>CC</sub> =0 or 3.3V, V <sub>IN</sub> =-7V	-100			μA
Positive-going input threshold voltage	V <sub>IT+</sub>	-7V≤V <sub>CM</sub> ≤12V			200	mV
Negative-going input threshold voltage	V <sub>IT-</sub>	-7V≤V <sub>CM</sub> ≤12V	-200			mV
Hysteresis voltage	V <sub>hys</sub>	-7V≤V <sub>CM</sub> ≤12V	10	30		mV
High level output voltage	V <sub>OH</sub>	I <sub>OUT</sub> =-2.5mA, V <sub>ID</sub> =200 mV	V <sub>cc</sub> -1.5			V
Low level output voltage	V <sub>OL</sub>	I <sub>OUT</sub> =2.5mA, V <sub>ID</sub> =-200 mV			0.4	V
Tristate leakage current	I <sub>OZR</sub>	0.4V <v<sub>0&lt;2.4V</v<sub>			±1	μA
Receiver input resistance	R <sub>IN</sub>	-7V≤V <sub>CM</sub> ≤12V	96			kΩ
Receiver short-circuit current	I <sub>OSR</sub>	0V≤V <sub>O</sub> ≤V <sub>CC</sub>	±8		±60	mA

(unless otherwise stated  $V_{CC}$ =3.3V±10%, Temp= $T_{MIN}$ ~ $T_{MAX}$ , typical value is  $V_{CC}$ =+3.3V, Temp=25°C)

## 8. Supply Current

Parameter	Symbol	Conditions	Min	Тур	Max	Units
Supply current	I <sub>CC1</sub>	/RE=0V, DE=0V		520	800	μA
Supply current	I <sub>CC2</sub>	/RE=V <sub>CC</sub> , DE=V <sub>CC</sub>		540	700	μΑ







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## 9. Driver Switching Characteristics

Parameter	Symbol	Conditions	Min	Тур	Max	Units
Driver differentialoutput delay	t <sub>DD</sub>	B -600 C -C -15pE	1	22	35	ns
Driver differentialoutput transition time	t <sub>TD</sub>	$R_L=60\Omega$ , $C_{L1}=C_{L2}=15pF$	3	11	25	ns
Driver propagationdelay, low-to-high	t <sub>PLH</sub>		7	23	35	ns
Driver propagationdelay, high-to-low	t <sub>PHL</sub>	$R_L$ =27 $\Omega$	7	23	35	ns
t <sub>PLH</sub> - t <sub>PHL</sub>	t <sub>PDS</sub>			-1.4	±8	ns
Driver enable to output high	t <sub>PZH</sub>			42	90	ns
Driver enable to output low	t <sub>PZL</sub>			42	90	ns
Driver disable time from low	t <sub>PLZ</sub>	$R_L$ =110 $\Omega$		35	80	ns
Driver disable time from high	t <sub>PHZ</sub>			35	80	ns
Driver enable from shutdownto output high	t <sub>PSH</sub>			650	900	ns
Driver enable from shutdownto output low	t <sub>PSL</sub>			650	900	ns



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## 10. Receiver Switching Characteristics

Parameter	Symbol	Conditions	Min	Тур	Max	Units
Receiver input to outputdelay (low to high)	t <sub>RPLH</sub>	C <sub>L</sub> =15pF		80	150	ns
Receiver input to outputdelay (high to low)	t <sub>RPHL</sub>	See Figure 7 and Figure 8		80	150	ns
t <sub>RPLH</sub> - t <sub>RPHL</sub>	t <sub>RPDS</sub>	See Figure 7 and Figure 6		7	10	ns
Receiver enable tooutput low	t <sub>RPZL</sub>			20	50	ns
Receiver enable tooutput high	f <sub>RPZH</sub>			20	50	ns
Receiver disable time from low	t <sub>PRLZ</sub>			20	45	ns
Receiver disable time from high	f <sub>PRHZ</sub>	C <sub>L</sub> =15pF		20	45	ns
Receiver enable from	f <sub>RPSH</sub>	See Figure 7 and Figure 8		200	1400	ns
shutdown to output high	IKPSH			200	1400	
Receiver enable from	t <sub>RPSL</sub>			200	1400	ns
shutdown to output low	*KPSL			200	1400	113
Time to shutdown	t <sub>shon</sub>	NOTE2	80		300	ns

NOTE2: The device is put into shutdown by bringing RE high and DE low. If the enable inputs are in this state for less than 80ns, the device is guaranteed not to enter shutdown. If the enable inputs are in this state for at least 300ns, the device is guaranteed to have entered shutdown.





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## 11.Function Table

### Driver

Cor	Control		Output				
/RE	DE	DI	Α	В			
Х	1	1	Н	L			
Х	1	0	L	Н			
0	0	Х	Z Z				
1 0 X Z (shutdown)							
X: don't care; Z: high impedance							

### Receiver

Con	itrol	Input	Output				
/RE	DE	A-B	RO				
0	X	≥200mV	Н				
0	Х	≤-200mV	L				
0	Х	Open/short- circuit	Н				
1	Х	Х	Z				
X: do	X: don't care; Z: high impedance						



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### 12.Test Circuit

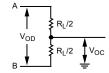


Figure 1. Driver Differential Output Voltage and Common-Mode Output Voltage

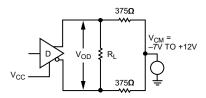


Figure 2. Driver Differential Output Voltage with Varying Common-Mode Voltage

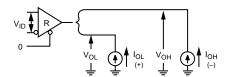
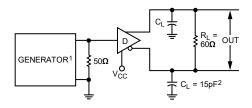


Figure 3. Receiver Output Voltage High and Output Voltage Low



 $^{1}$ PPR=250kHz, 50% DUTY CYCLE,  $t_{R}$ ≤6.0ns,  $Z_{0}$ =50Ω.  $^{2}$ C<sub>L</sub> INCLUDES PROBE AND STRAY CAPACITANCE.

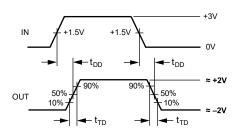
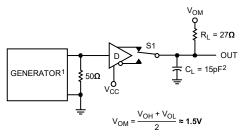


Figure 4. Driver Differential Output Delay and Transition Times



<sup>1</sup>PPR=250kHz, 50% DUTY CYCLE, t<sub>R</sub>≤6.0ns, Z<sub>0</sub>=50Ω. <sup>2</sup>C<sub>L</sub> INCLUDES PROBE AND STRAY CAPACITANCE.

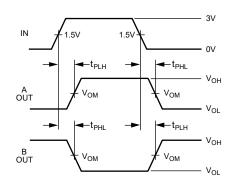
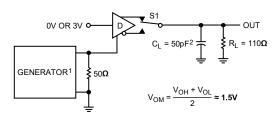


Figure 5. Driver Propagation Delays



 $^{1}$ PPR=250kHz, 50% DUTY CYCLE,  $^{1}$ t<sub>R</sub>≤6.0ns,  $^{2}$ C<sub>L</sub>INCLUDES PROBE AND STRAY CAPACITANCE.

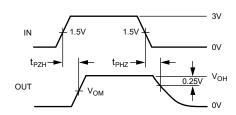


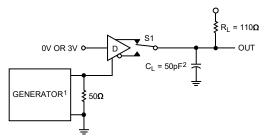
Figure 6. Driver Enable and Disable Times (tpzh, tpsh, tphz)



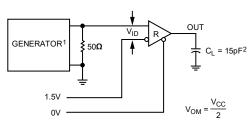




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 $^1\text{PPR} = 250\text{kHz},\, 50\%$  DUTY CYCLE,  $t_R\!\!\le\!\!6.0\text{ns},\, Z_0\!\!=\!\!50\Omega.$   $^2C_L$  INCLUDES PROBE AND STRAY CAPACITANCE.



 $^1\text{PPR} = 250\text{kHz},\, 50\%$  DUTY CYCLE,  $t_R\!\!\le\!\!6.0\text{ns},\, Z_0\!\!=\!\!50\Omega.$   $^2C_L$  INCLUDES PROBE AND STRAY CAPACITANCE.

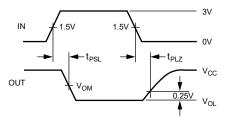


Figure 7. Driver Enable and Disable Times  $(t_{PZL},\,t_{PSL},\,t_{PLZ})$ 

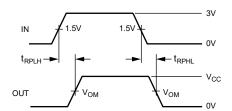
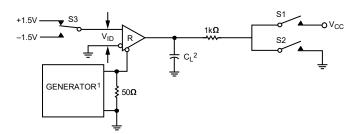


Figure 8. Receiver Propagation Delays



 $^1\text{PPR} = 250\text{kHz},\, 50\%$  DUTY CYCLE,  $t_R \!\! \leq \!\! 6.0\text{ns},\, Z_0 \!\! = \!\! 50\Omega.$   $^2C_L$  INCLUDES PROBE AND STRAY CAPACITANCE.



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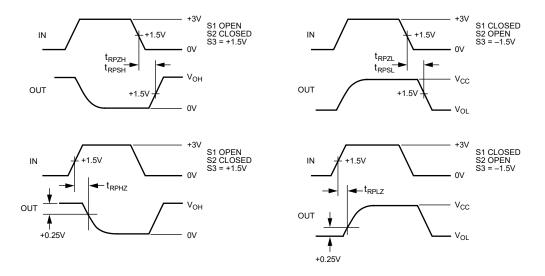


Figure 9. Receiver Enable and Disable Times







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### 13.General Description

#### 1 Brief description

The ADM3485E is a half-duplex high-speed transceiver for RS-485/RS-422 communication, and includes one driver and one receiver. It has fail-safe, over-voltage protection and over-current protection. The ADM3485E allows errorfree data transmission up to 12Mbps.

#### 2 Allowing up to 256 transceivers on the bus

The standard RS-485 receiver has an input impedance of  $12k\Omega$  (1 unit load), and the standard driver can drive up to 32 unit loads. The receiver of the ADM3485E transceiver has a 1/8 unit load receiver input impedance ( $96k\Omega$ ), allowing up to 256 transceivers to be connected in parallel on one bus. These devices can be combined arbitrarily, or combined with other RS-485 transceivers, as long as the total load does not exceed 32 units.

#### 3 Driver output protection

Two mechanisms are used to avoid faults or bus collisions that cause excessive output current and excessive power consumption. First, over-current protection provides fast short-circuit protection over the entire common-mode voltage range (refer to the typical operating characteristics). Second, the thermal shutdown circuit forces the driver output into a high impedance state when the die temperature exceeds 140°C.

#### 4 Typical applications

4.1 Bus networking: The ADM3485E RS485 transceiver is designed for bidirectional data communication on multipoint bus transmission lines. Figure 10 shows a typical network application circuit. These devices can also be used as linear repeaters with cables longer than 4000 feet. In order to reduce reflections, terminal matching should be done at both ends of the transmission line with their characteristic impedance, and the length of the branch wires other than the main line should be as short as possible.



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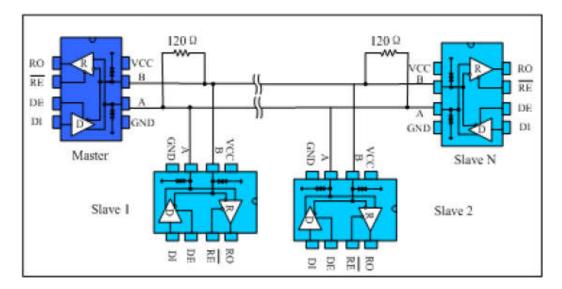


Figure 10. Bus-type RS485 half-duplex communication network

#### 4.2 Hand-in-hand networking:

Also known as daisy chain topology, it is the standard and specification of RS485

bus wiring, and is the RS485 bus topology recommended by organizations such as TIA. The wiring method is that the master control device and multiple slave devices form a hand-in-hand connection, as shown in Figure 11, the hand-in-hand way is to leave no branches. This wiring method has the advantages of low signal reflection and high communication success rate.







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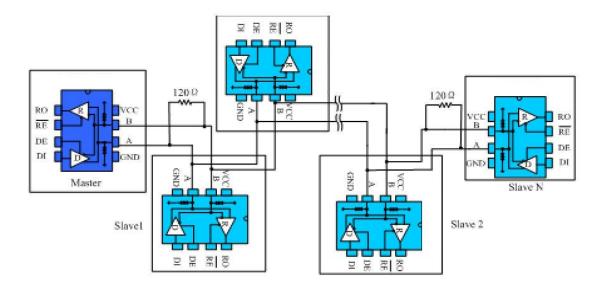


Figure 11. Hand-in-hand type RS485 half-duplex communication network

#### 4.2 Hand-in-hand networking:

In harsh environments, RS485 communication ports are usually protected against static electricity, lightning and surge protection, etc. and it is even necessary to prevent 380V power supply access to avoid damage of smart meters and industrial control hosts. Figure 12 shows 3 common kinds of RS485 bus port protection schemes. The first scheme is to connect the TVS device to the protection ground in parallel with the AB port, the TVS device in parrallel with the AB port, the thermistor in series with the AB port and the gas discharge tube is connected to the protection ground to form a three-level protection scheme. The second scheme is a threelevel protection scheme including TVS connected to the ground in parallel with AB, the thermistor in series and the varistor in parallel with AB. The third one includes pull-down resistors connected to the power supply and ground respectively for AB, TVS between AB and the thermistor connected to A or B port.



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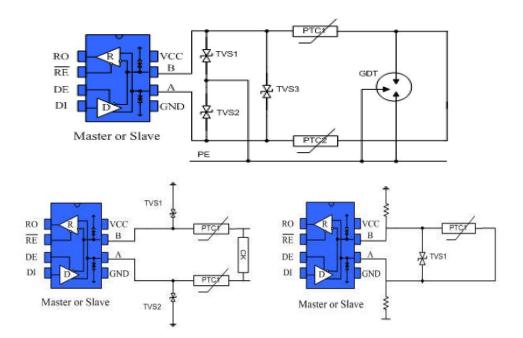
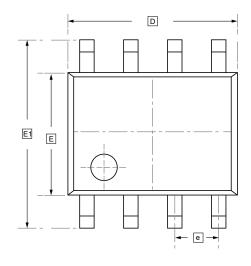


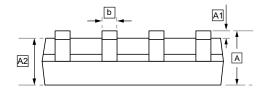
Figure 12. Port protection scheme

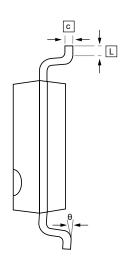


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## 14.SOP-8 Package Outline Dimensions







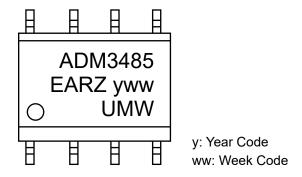
### **DIMENSIONS** (mm are the original dimensions)

Symbol	Α	<b>A</b> 1	A2	b	C	D	Е	E1	е	L	θ
Min	1.350	0.000	1.350	0.330	0.170	4.700	3.800	5.800	1.270	0.400	0°
Max	1.750	0.100	1.550	0.510	0.250	5.100	4.000	6.200	BSC	1.270	8°



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## 15.Ordering information



Order Code	Package	Base QTY	Delivery Mode		
UMW ADM3485EARZ	SOP-8	2500	Tape and reel		







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### 16.Disclaimer

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